ON THE DISSIPATION LAYER OF RADIAL BEARINGS

R.O. AYENI, S.S. OKOYA and C.J. AGORZIE

Department of Mathematics
University of Ife
Ile-Ife, Nigeria

(Received May 14, 1986)

ABSTRACT. The dissipation boundary layer of certain radial bearings is identified. It is shown that, under certain conditions, the temperature outside this layer is constant.

KEY WORDS AND PHRASES. Dissipation boundary layer, variable viscosity, coupled momentum and energy equations, thin lubricating oils.

1980 AMS SUBJECT CLASSIFICATION CODE. 80A20.

1. INTRODUCTION.

In paper [1], we discussed the solution to the coupled momentum and energy equations

\[ \frac{\partial \dot{\gamma}}{\partial t} = Pr \frac{\partial}{\partial y} \left( \exp \left( \frac{\lambda_1}{\theta + \lambda_2} \right) \frac{\partial \dot{\gamma}}{\partial y} \right), \]

\[ \frac{\partial \theta}{\partial t} = \frac{\partial^2 \theta}{\partial y^2} - \left( \frac{\partial \theta}{\partial y} \right)^2 + \Delta \exp \left( \frac{\theta + \lambda_1}{\theta + \lambda_2} \right) \left( \frac{\partial \dot{\gamma}}{\partial y} \right)^2 \]

where \( \lambda_1, \lambda_2 \) and \( \Delta \) are constants.

The boundary and initial conditions are

\[ \frac{\partial \dot{\gamma}}{\partial y}(0,t) = - \frac{B}{\sqrt{\gamma}}. \dot{\gamma}(0,t) \quad \text{given, } \dot{\gamma}(\infty,t) = 0 \]

\[ \dot{\gamma}(y,0) = 0 \]

\[ \theta(0,t) = \theta(\infty,t) = 0 \]

\[ \theta(y,0) = 0 \]

The above equations arose from investigations on the flow of thin lubricating oils.

Earlier in [2], we discussed the thermal runaway of variable viscosity flows between concentric cylinders - there is a wide gap between the cylinders and we show that, under certain conditions which affect the Peclet number, the reduced Reynolds number and the Nahme-Griffith number, the width of the thermal boundary layer is \( O(R) \) where \( R \) is the radius of the inner cylinder. Under the same assumptions, there exists a dissipation boundary layer of width \( O(R/G^2) \) where \( G \) is the Nahme-Griffith number.

In the case of radial bearings, the width, \( h \), of the lubricant is small and thus if \( R_1, R_2 \) are the radii of the shaft and the bearing then

\[ R_i >> h. \quad i = 1, 2 \]
(1.7) implies that as a first approximation, we may regard the shaft and the bearing as flat surfaces, that is $R_1 = \infty$ when $h$ is the standard measure. We therefore need to investigate the boundary layer of the lubrication problem although $0(R/G) = \infty$ is adequate for [2].

2. DISSIPATION BOUNDARY LAYER.

Shampine [3] investigated the problem

$$\frac{\partial c}{\partial t} = \frac{\partial}{\partial x} \left( D(c) \frac{\partial c}{\partial x} \right),$$

$$c(0,t) = 1, \quad \frac{\partial c}{\partial x}(0,t), \quad \text{given}$$

(2.1)

(2.2)

He showed that if

$$-D(1) \frac{\partial c}{\partial t}(0,t) = \frac{1}{2} + \max D(c),$$

then there is an $\eta_1 < 1$ such that $c(\eta_1) = 0$, where $\eta = x/\sqrt{c}$. For the proof of this, see [3].

In this paper as in [1], we have

$$\Pr \exp\left(\frac{\lambda_1}{\beta \lambda_2}\right)$$

in the plane of $D(c)$ above, but a careful study of the proof advanced by Shampine showed that his result is true for (1.1). That is, there exists an $\eta_1 < 1$ such that if

$$B = 1 + \frac{1}{2} e^{-\lambda_2}$$

(2.3)

then there exists an $\eta_1 < 1$ such that $\phi(\eta_1) = 0$ and $\phi(\eta) \equiv 0$ for $\eta \geq \eta_1$. This leads to

THEOREM. Let (1.1), (1.2) (1.3) (1.6), and (2.3) hold. Then there exists an $\eta_2 < 1$ such that $\theta(\eta_2) = 0$ and $\theta(\eta) \equiv 0$ and $\eta \geq \eta_2$.  

PROOF. $\phi(\eta_1) \equiv 0$ for $\eta \geq \eta_1$

implies $\frac{\partial \phi}{\partial y} \equiv 0$ for $\eta > \eta_1$.

That is, $\frac{\partial \phi}{\partial y} \equiv 0$ for $\eta \geq \eta_2 = \eta_1$.

Hence $\theta \equiv 0$ for $\eta \geq \eta_2$.

3. PHYSICAL INTERPRETATION.

The above theorem shows that at time $t$ the heat generated has only penetrated to $y = \eta_2 \sqrt{c}$. This identifies the dissipation layer. The viscosity of the lubricant outside this layer is not affected by heat under the conditions assumed in this problem.

REFERENCES


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**Guest Editors**

Lean Yu, Academy of Mathematics and Systems Science, Chinese Academy of Sciences, Beijing 100190, China; Department of Management Sciences, City University of Hong Kong, Tat Chee Avenue, Kowloon, Hong Kong; yulean@amss.ac.cn

Shouyang Wang, Academy of Mathematics and Systems Science, Chinese Academy of Sciences, Beijing 100190, China; sywang@amss.ac.cn

K. K. Lai, Department of Management Sciences, City University of Hong Kong, Tat Chee Avenue, Kowloon, Hong Kong; mskklai@cityu.edu.hk